CHAPTER - 8
CHAPTER-8

Scope for further work

1. To find practical applications of catalogues of simple jointed planar kinematic chains and their inversions obtained by the proposed methodology.
2. To derive equivalent mechanism for synthesized simple jointed planar kinematic chains by the proposed methodology of the types listed below,
   - Hydraulic piston cylinder mechanism
   - Cam - linkage or gear - linkage mechanism
   - Belt pulley or sprocket - chain mechanism
   - Spring mechanism
3. To extend methodology for synthesis of multiple - jointed planar kinematic chains.
4. To extend work to synthesize spatial chains.