

CHAPTER - 8

CHAPTER- 8

Scope for further work

1. To find practical applications of catalogues of simple jointed planar kinematic chains and their inversions obtained by the proposed methodology.
2. To derive equivalent mechanism for synthesized simple jointed planar kinematic chains by the proposed methodology of the types listed below.
 - Hydraulic piston cylinder mechanism
 - Cam – linkage or gear – linkage mechanism
 - Belt pulley or sprocket – chain mechanism
 - Spring mechanism
3. To extend methodology for synthesis of multiple – jointed planar kinematic chains.
4. To extend work to synthesize spatial chains.

पं० रविशंकर शुक्ल विश्वविद्यालय
"18745"
T 18745

ग्रन्थ काड
प्राप्ति क्रमांक 18745 जिल्हा
वर्गांक 621 VBA 6
ग्रन्थांक

पं० रविशंकर शुक्ल विश्वविद्यालय
ग्रन्थागार
रायपुर (मं. प्र०)