REFERENCES


computer algebra’, Proceedings of the IEEE International symposium
on computer aided control system design, USA, pp 48–53.

to digital PID controller design’, IEEE transactions on automatic
control, Vol.48, No.4, pp.687-692.


robust control’, UKACC International conference on control, pp.1328-
1332.

bounded noise ARX signals’, IEEE transactions on automatic control,
Vol.26, No.2, pp.325-331.

Robust Control for Power Station Processes’, IEEE Transactions on

dynamics identification’, Proceedings of IEEE Mediterranean electro

7th edition.

Annealing for Optimal robot arm PID Control’, Proceedings of the
1st IEEE conference on evolutionary computing, Vol.2, pp. 707-713.

linear regulators with steady – state trajectory insensitivity’

Model Control (IMC) approach for designing disk drive servo
controller’, IEEE transactions on industrial electronics, Vol.42, No.3,
pp.248-256.

feedforward neural networks’, International journal of control, Vol.61,
No.3, pp.533–547.


