

## Chapter 2

# Oscillation of Impulsive Hyperbolic Differential Equations with Distributed Delay

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# Oscillation of Impulsive Hyperbolic Differential Equations with Distributed Delay

## 2.1 Introduction

In recent times, there has been rising interest in studying the oscillation and nonoscillation results of partial differential equations with continuous distributed deviating arguments [21, 22, 49, 51, 63, 68, 73, 75, 77]. The study of impulsive partial differential equations is motivated by having many applications in population models [9, 25], single species growth [23], quenching problems [13] and various scientific models [78, 80] with the boundary conditions of the type Dirichlet, Neumann and Robin. In this chapter, we focus on oscillation of impulsive second order partial differential equations with distributed deviating arguments

$$\left. \begin{aligned}
 \frac{\partial^2 u}{\partial t^2} &= a(t)\Delta u(x, t) + b(t)\Delta u(x, \tau(t)) - \sum_{i=1}^n r_i(x, t)u(x, \sigma_i(t)) \\
 &+ \int_c^d q(x, t, \xi)f(u(x, g(t, \xi)))d\eta(\xi), \quad t \neq t_k, \quad (x, t) \in \Omega \times (0, +\infty) \equiv G, \\
 u(x, t_k^+) &= (1 + \alpha_k)u(x, t_k) \\
 u_t(x, t_k^+) &= (1 + \beta_k)u_t(x, t_k), \quad k = 1, 2, \dots,
 \end{aligned} \right\} \tag{2.1.1}$$

with the boundary condition

$$u = 0, \quad (x, t) \in \partial\Omega \times (0, +\infty), \tag{2.1.2}$$

Problem (2.1.1) is more generalization of the following equation

$$\begin{aligned} \frac{\partial^2 u}{\partial t^2} &= a(t)\Delta u(x, t) + \sum_{i=1}^m a_i(t)\Delta u(x, \rho_i(t)) - \sum_{j=1}^k p_j(x, t)u(x, \sigma_j(t)) + f(x, t), \\ &\quad (x, t) \in \Omega \times (0, \infty) \equiv G, \end{aligned} \quad (2.1.3)$$

with impulse and distributed delay, which was studied by Baotong et al. [11] and also (2.1.1) includes the following equations

$$\begin{aligned} \frac{\partial^2 u}{\partial t^2} &= a(t)\Delta u(x, t) + b(t)\Delta u(x, \tau(t)) - \sum_{i=1}^n r_i(x, t)u(x, \sigma_i(t)) \\ &+ \sum_{j=1}^l q_j(x, t)f_j(u(x, g(t))), \quad t \neq t_k, \quad (x, t) \in \Omega \times (0, +\infty) \equiv G, \\ u(x, t_k^+) &= (1 + \alpha_k)u(x, t_k) \\ u_t(x, t_k^+) &= (1 + \beta_k)u_t(x, t_k), \quad k = 1, 2, \dots, \end{aligned}$$

In this chapter, we assume that the following hypotheses hold:

(H<sub>1</sub>)  $a(t), b(t) \in PC([0, +\infty), [0, +\infty))$ , where  $PC$  represents the class of functions

which are piecewise continuous in  $t$  with discontinuities of first kind only at

$t = t_k, k = 1, 2, \dots$ , and left continuous at  $t = t_k, k = 1, 2, \dots$ .

(H<sub>2</sub>)  $r_i(x, t) \in C(\bar{\Omega} \times [0, +\infty), [0, +\infty))$ ,  $R_i(t) = \min_{x \in \bar{\Omega}} r_i(x, t)$ ,

$q(x, t, \xi) \in C(\bar{\Omega} \times \mathbb{R}^+ \times [c, d], \mathbb{R}^+)$ ,  $Q(t, \xi) = \min_{x \in \bar{\Omega}} q(x, t, \xi)$ ,  $f(u) \in C(\mathbb{R}, \mathbb{R})$  is

convex in  $\mathbb{R}^+$ ,  $uf(u) > 0$  and  $\frac{f(u)}{u} \geq \epsilon > 0$  for  $u \neq 0$ .

(H<sub>3</sub>)  $\tau(t) \in C([0, \infty), \mathbb{R})$ ,  $\lim_{t \rightarrow \infty} \tau(t) = +\infty$ ,  $\sigma_i(t) \in C([0, +\infty), \mathbb{R})$ ,  $\lim_{t \rightarrow +\infty} \sigma_i(t) = \infty$ ,

$\sigma(t) = \max_{1 \leq i \leq n} \sigma_i(t)$ ,  $i = 1, 2, \dots, n$ ,  $g(t, \xi) \in C(\mathbb{R}^+ \times [c, d], \mathbb{R})$ ,  $g(t, \xi) \leq t$  for

$\xi \in [c, d]$  and  $g(t, \xi)$  is nondecreasing with respect to  $t$  and  $\xi$  respectively and

$\liminf_{t \rightarrow \infty, \xi \in [c, d]} g(t, \xi) = +\infty$ ,  $\eta(\xi) : [c, d] \rightarrow \mathbb{R}$  is nondecreasing and the integral is a

stieltjes integral in (2.1.1).

(H<sub>4</sub>)  $u(x, t)$  and  $u_t(x, t)$  are piecewise continuous in  $t$  with discontinuities of first

kind only at  $t = t_k, k = 1, 2, \dots$ , and left continuous at  $t = t_k, \alpha_k > -1$ ,

$\beta_k > -1$ ,  $\alpha_k < \beta_k$ , the sequence  $t_k$  is a fixed strictly increasing sequence of positive real numbers with  $t_k \rightarrow \infty$  as  $k \rightarrow \infty$ .

We begin with definitions, known results, notations and Lemma which are required to prove main results.

**Definition 2.1.1.** *A solution  $u$  of the problem (2.1.1) is a function*

*$u \in C^2(\bar{\Omega} \times [t_{-1}, +\infty), \mathbb{R}) \cap C(\bar{\Omega} \times [\hat{t}_{-1}, +\infty), \mathbb{R})$  that satisfies (2.1.1), where*

$$t_{-1} := \min \left\{ 0, \min_{\xi \in [c,d]} \left\{ \inf_{t \geq 0} g(t, \xi) \right\} \right\}, \quad \hat{t}_{-1} := \min \left\{ 0, \inf_{t \geq 0} \tau(t), \min_{1 \leq s \leq n} \left\{ \inf_{t \geq 0} \sigma_i(t) \right\} \right\}.$$

Now with this definition of solution, we can precisely define what we mean by oscillation.

**Definition 2.1.2.** *The solution  $u$  of the problem (2.1.1)-(2.1.2) is said to be oscillatory in the domain  $G$  if for any positive number  $\ell$  there exists a point  $(x_0, t_0) \in \Omega \times [\ell, +\infty)$  such that  $u(x_0, t_0) = 0$  holds.*

**Definition 2.1.3.** *A function  $U(t)$  is said to be eventually positive (negative), if there exists a  $t_1 \geq t_0$  such that  $U(t) > 0$  ( $< 0$ ) holds for all  $t \geq t_1$ .*

It is identified that [72] the least eigenvalue  $\lambda_0 > 0$  of the eigenvalue problem

$$\begin{aligned} \Delta \omega(x) + \lambda \omega(x) &= 0, \quad \text{in } \Omega, \\ \omega(x) &= 0, \quad \text{on } \partial \Omega, \end{aligned}$$

and the consequent eigen function  $\Phi(x) > 0$  in  $\Omega$ .

For each positive solution  $u(x, t)$  of the problem (2.1.1)-(2.1.2) we define the functions

$$U(t) = K_{\Phi} \int_{\Omega} u(x, t) \Phi(x) dx,$$

and

$$G(t) = \epsilon \int_c^d Q(t, \xi) d\eta(\xi).$$

**Lemma 2.1.1.** [11] Suppose that  $y(t) \in C^2([t_0, \infty), \mathbb{R})$  and that

$$y(t) > 0, \quad y'(t) > 0 \quad \text{and} \quad y''(t) \leq 0 \quad \text{for} \quad t \geq t_0 > 0.$$

Then for any  $\lambda_1 \in (0, 1)$ , there exists a number  $t_1 > t_0$  such that

$$y(t) \geq \lambda_1 t y'(t) \quad \text{for} \quad t \geq t_1.$$

## 2.2 Main Results

In this section, we establish some sufficient conditions for the oscillation of all solutions of the problem (2.1.1)-(2.1.2).

**Theorem 2.2.1.** Suppose that conditions  $(H_1)$ - $(H_4)$  hold and that every solution  $u(x, t)$  of the problem (2.1.1)-(2.1.2) is oscillatory in  $G$ , if the impulsive delay differential inequality

$$\left. \begin{aligned} U''(t) + \sum_{i=1}^n R_i(t)U(\sigma_i(t)) - G(t)U(g(t, \xi)) &\leq 0, & t \neq t_k, & t \geq t_1, \\ U(t_k^+) &= (1 + \alpha_k)U(t_k) \\ U'(t_k^+) &= (1 + \beta_k)U'(t_k), & k = 1, 2, \dots, \end{aligned} \right\} \quad (2.2.1)$$

has no eventually positive solutions.

**Proof.** Let  $u(x, t)$  be a nonoscillatory solution of the boundary value problem (2.1.1)-(2.1.2) and  $u(x, t) > 0$ . Then there exists a  $t_1 > t_0 > 0$  such that  $\tau(t) \geq 0$ ,

$\sigma_i(t) \geq 0$  and  $g(t, \xi) \geq 0$  for  $(t, \xi) \in [t_1, +\infty) \times [c, d]$ , we get that

$$u(x, \tau(t)) > 0, \quad \text{for } (x, t) \in \Omega \times [t_1, +\infty),$$

$$u(x, \sigma_i(t)) > 0, \quad \text{for } (x, t) \in \Omega \times [t_1, +\infty), \quad i = 1, 2, \dots, n,$$

$$\text{and } u(x, g(t, \xi)) > 0, \quad \text{for } (x, t, \xi) \in \Omega \times [t_1, +\infty) \times [c, d].$$

Multiplying both sides of (2.1.1) by  $K_\Phi \Phi(x) > 0$  and integrating with respect to  $x$  over  $\Omega$ , we obtain

$$\begin{aligned} \frac{\partial^2}{\partial t^2} \left[ \int_{\Omega} u(x, t) K_\Phi \Phi(x) dx \right] &= a(t) \int_{\Omega} \Delta u(x, t) K_\Phi \Phi(x) dx + b(t) \int_{\Omega} \Delta u(x, \tau(t)) K_\Phi \Phi(x) dx \\ &\quad - \sum_{i=1}^n \int_{\Omega} r_i(x, t) u(x, \sigma_i(t)) K_\Phi \Phi(x) dx + \int_{\Omega} \int_c^d q(x, t, \xi) f(u(x, g(t, \xi))) K_\Phi \Phi(x) d\eta(\xi) dx \end{aligned} \quad (2.2.2)$$

From Green's formula and the boundary condition (2.1.2), we see that

$$\begin{aligned} K_\Phi \int_{\Omega} \Delta u(x, t) \Phi(x) dx &= K_\Phi \int_{\partial\Omega} \left[ \Phi(x) \frac{\partial u}{\partial \gamma} - u \frac{\partial \Phi(x)}{\partial \gamma} \right] dS + K_\Phi \int_{\Omega} u(x, t) \Delta \Phi(x) dx \\ &= -\lambda_0 U(t). \end{aligned}$$

$$\therefore K_\Phi \int_{\Omega} \Delta u(x, t) \Phi(x) dx \leq 0 \quad (2.2.3)$$

and

$$\begin{aligned} K_\Phi \int_{\Omega} \Delta u(x, \tau(t)) \Phi(x) dx &= K_\Phi \int_{\partial\Omega} \left[ \Phi(x) \frac{\partial u(x, \tau(t))}{\partial \gamma} - u(x, \tau(t)) \frac{\partial \Phi(x)}{\partial \gamma} \right] dS \\ &\quad + K_\Phi \int_{\Omega} u(x, \tau(t)) \Delta \Phi(x) dx \\ &= -\lambda_0 U(\tau(t)) \end{aligned}$$

$$\therefore K_\Phi \int_{\Omega} \Delta u(x, \tau(t)) \Phi(x) dx \leq 0. \quad (2.2.4)$$

Furthermore applying Jensen's inequality for convex functions and using the assumptions in  $(H_2)$ , we get that

$$\int_{\Omega} \int_c^d q(x, t, \xi) f(u(x, g(t, \xi))) K_\Phi \Phi(x) d\eta(\xi) dx$$

$$\begin{aligned}
&\geq \int_c^d Q(t, \xi) \int_{\Omega} f(u(x, g(t, \xi))) K_{\Phi} \Phi(x) dx d\eta(\xi) \\
&\geq \int_c^d Q(t, \xi) \epsilon \int_{\Omega} u(x, g(t, \xi)) K_{\Phi} \Phi(x) dx d\eta(\xi) \\
&\geq \epsilon \int_c^d Q(t, \xi) U(g(t, \xi)) d\eta(\xi), \tag{2.2.5}
\end{aligned}$$

where  $U(g(t, \xi)) = \int_{\Omega} u(x, g(t, \xi)) K_{\Phi} \Phi(x) dx$ .

Combining (2.2.2)-(2.2.5), we get that

$$\begin{aligned}
U''(t) &\leq - \sum_{i=1}^n \int_{\Omega} R_i(t) u(x, \sigma_i(t)) K_{\Phi} \Phi(x) dx + \epsilon \int_c^d Q(t, \xi) U(g(t, \xi)) d\eta(\xi), \\
U''(t) &\leq - \sum_{i=1}^n R_i(t) U(\sigma_i(t)) + G(t) U(g(t, \xi)), \\
U''(t) + \sum_{i=1}^n R_i(t) U(\sigma_i(t)) - G(t) U(g(t, \xi)) &\leq 0, \quad t \neq t_k, \quad t \geq t_1,
\end{aligned}$$

where  $G(t) = \epsilon \int_c^d Q(t, \xi) d\eta(\xi)$ . Also, multiplying both sides of (2.1.1) by

$K_{\Phi} \Phi(x) > 0$ , integrating with respect to  $x$  over  $\Omega$ , and from  $(H_4)$  we obtain

$$\begin{aligned}
\int_{\Omega} u(x, t_k^+) K_{\Phi} \Phi(x) dx &= (1 + \alpha_k) \int_{\Omega} u(x, t_k) K_{\Phi} \Phi(x) dx, \\
U(t_k^+) &= (1 + \alpha_k) U(t_k), \\
U'(t_k^+) &= (1 + \beta_k) U'(t_k), \quad t = t_k, k = 1, 2, \dots .
\end{aligned}$$

Therefore  $U(t)$  is an eventually positive solution of (2.2.1). This disagree with the hypothesis and completes the proof of the theorem.  $\square$

**Theorem 2.2.2.** *Suppose that conditions  $(H_1)$ - $(H_4)$  hold. If for every number  $\lambda_1, \lambda_2 \in (0, 1)$ ,*

$$\limsup_{t \rightarrow \infty} \int_{\sigma(t)}^t \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right) \left[ \sum_{i=1}^n \lambda_1 \sigma_i(s) R_i(s) - \lambda_2 G(s) g(s, \xi) \right] ds > 1, \tag{2.2.6}$$

*then every solution  $u(x, t)$  of the problem (2.1.1)-(2.1.2) is oscillatory in  $G$ .*

**Proof.** On the contrary, let  $u(x, t)$  be a nonoscillatory solution of the boundary value problem (2.1.1)-(2.1.2) which we assume to be positive. Now we can use

$$U''(t) + \sum_{i=1}^n R_i(t)U(\sigma_i(t)) - G(t)U(g(t, \xi)) \leq 0, \quad t \geq t_1.$$

By Lemma 2.1.1

$$U(\sigma_i(t)) \geq \lambda_1 \sigma_i(t) U'(\sigma_i(t)) \quad \text{and} \quad U(g(t, \xi)) \geq \lambda_2 g(t, \xi) U'(g(t, \xi)), \quad t \geq t_1,$$

which implies that

$$U''(t) + \sum_{i=1}^n R_i(t) \lambda_1 \sigma_i(t) U'(\sigma_i(t)) - G(t) \lambda_2 g(t, \xi) U'(g(t, \xi)) \leq 0, \quad t \geq t_1. \quad (2.2.7)$$

Define

$$W(t) := \prod_{t_0 \leq t_k < t} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U(t).$$

In fact,  $W(t)$  is continuous on each interval  $[t_k, t_{k+1}]$ , and in consideration of  $W(t_k^+) \leq \left( \frac{1 + \beta_k}{1 + \alpha_k} \right) W(t_k)$ , it follows for  $t \geq t_0$  that, inequality (2.2.7) has no eventually positive solution, if the following inequality has no eventually positive solution.

$$W''(t) + \sum_{i=1}^n \lambda_1 \sigma_i(t) R_i(t) W'(\sigma_i(t)) - \lambda_2 G(t) g(t, \xi) W'(g(t, \xi)) \leq 0, \quad t \geq t_1.$$

Where

$$W(t_k^+) = \prod_{t_0 \leq t_j \leq t_k} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U(t_k^+) = \prod_{t_0 \leq t_j \leq t_k} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U(t_k) = W(t_k),$$

$$W(t_k^-) = \prod_{t_0 \leq t_j \leq t_{k-1}} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U(t_k^-) = \prod_{t_0 \leq t_j < t_k} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U(t_k) = W(t_k).$$



Which implies that,  $W(t)$  is continuous on  $[t_0, +\infty)$ . Then we get that

$$\begin{aligned} \prod_{t_0 \leq t_k < t} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-2} U''(t) + \sum_{i=1}^n \lambda_1 \sigma_i(t) R_i(t) \prod_{t_0 \leq t_k < t} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U'(\sigma_i(t)) \\ - \lambda_2 G(t) g(t, \xi) \prod_{t_0 \leq t_k < t} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U'(g(t, \xi)) \leq 0. \end{aligned}$$

Integrating the above inequality from  $\sigma(t)$  to  $t$ , we have

$$\begin{aligned} \int_{\sigma(t)}^t \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-2} U''(s) ds + \int_{\sigma(t)}^t \sum_{i=1}^n \lambda_1 \sigma_i(s) R_i(s) \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U'(\sigma_i(s)) ds \\ - \int_{\sigma(t)}^t \lambda_2 G(s) g(s, \xi) \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U'(g(s, \xi)) ds \leq 0 \end{aligned}$$

From this,

$$\begin{aligned} \prod_{t_0 \leq t_k < t} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-2} [U'(t) - U'(\sigma(t))] + \int_{\sigma(t)}^t \sum_{i=1}^n \lambda_1 \sigma_i(s) R_i(s) \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} \\ U'(\sigma_i(s)) ds - \int_{\sigma(t)}^t \lambda_2 G(s) g(s, \xi) \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right)^{-1} U'(g(s, \xi)) ds \leq 0, \quad t \geq t_1. \end{aligned}$$

Therefore,

$$\int_{\sigma(t)}^t \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right) \left[ \sum_{i=1}^n \lambda_1 \sigma_i(s) R_i(s) - \lambda_2 G(s) g(s, \xi) \right] ds \leq 1 - \frac{U'(t)}{U'(\sigma(t))} < 1,$$

and hence

$$\limsup_{t \rightarrow \infty} \int_{\sigma(t)}^t \prod_{t_0 \leq t_k < s} \left( \frac{1 + \alpha_k}{1 + \alpha_k} \right) \left[ \sum_{i=1}^n \lambda_1 \sigma_i(s) R_i(s) - \lambda_2 G(s) g(s, \xi) \right] ds \leq 1, \quad (2.2.8)$$

which is a contradiction with (2.2.6). The proof of the case  $u(x, t) < 0$  is similar and is omitted.  $\square$

## 2.3 Example

In this section, we present an example to point up the main results established in Section 2.2.

**Example 2.3.1.** Consider the following equation

$$\left. \begin{aligned} \frac{\partial^2 u}{\partial t^2} &= \frac{5}{2} \Delta u(x, t) + \Delta u(x, t - 3\pi/2) - \frac{5}{2} u(x, t - \pi) \\ &\quad - \int_{-\pi/2}^0 u(x, t + \xi) d\xi, \quad t > 1, t \neq t_k, k = 1, 2, \dots, \\ u(x, t_k^+) &= (1 + \alpha_k) u(x, t_k) \\ u_t(x, t_k^+) &= (1 + \beta_k) u_t(x, t_k), \quad k = 1, 2, \dots, \end{aligned} \right\} \quad (2.3.1)$$

for  $(x, t) \in (0, \pi) \times [0, +\infty)$ , with the boundary condition

$$u(0, t) = u(\pi, t) = 0. \quad (2.3.2)$$

Here  $\Omega = (0, \pi)$ ,  $a(t) = \frac{5}{2}$ ,  $b(t) = 1$ ,  $\tau(t) = t - \frac{3\pi}{2}$ ,  $n = 1$ ,  $R(t) = \frac{5}{2}$ ,  $\sigma(t) = t - \pi$ ,  $Q(t, \xi) = 1$ ,  $f(u) = u$ ,  $g(t, \xi) = t + \xi$ ,  $\alpha_k = \frac{1}{2^k}$ ,  $\beta_k = 2^k$ ,  $\epsilon = 1$ , and  $G(s) = \frac{\pi}{2}$ .

Also, we see from the above assumption that the hypotheses  $(H_1)$ - $(H_4)$  hold, moreover

$$\begin{aligned} \lim_{t \rightarrow +\infty} \int_{t_0}^t \prod_{t_0 \leq t_k < s} \left( \frac{1 + \beta_k}{1 + \alpha_k} \right) ds &= \int_1^{+\infty} \prod_{1 < t_k < s} \left( \frac{1 + 2^k}{1 + (1/2^k)} \right) ds \\ &= \int_1^{t_1} \prod_{1 < t_k < s} 2^k ds + \int_{t_1^+}^{t_2} \prod_{1 < t_k < s} 2^k ds + \int_{t_2^+}^{t_3} \prod_{1 < t_k < s} 2^k ds + \dots \\ &= +\infty. \end{aligned}$$

Now, the condition (2.2.6) reads,

$$\limsup_{t \rightarrow \infty} \int_{t-\pi}^t \left( \prod_{t_0 \leq t_k < s} 2^k \right) \left[ \frac{5}{6}(s - \pi) + \frac{\pi}{8}(s + \xi) \right] ds > 1. \quad (2.3.3)$$

Therefore all the conditions of the Theorem 2.2.2 are satisfied. So, every solution of the problem (2.3.1)-(2.3.2) is oscillatory in  $G$ . In fact  $u(x, t) = \sin x \cos t$  is such a solution.