

APPENDIX - I

The Spectral Observer may operate with any sampling interval Δt . In general, $2N + 1$ samples are required for convergence to determine the harmonic contents of the band-limited signal $y(t)$. A general method of gain coefficient calculation is to temporarily transform the system to the dual of the phase variable canonical form [5, 6, 7, 8]

$$\xi' = Q\xi$$

$$\xi'(k+1) = (Q\phi Q^{-1}) \xi'(k) + Qg[y - c^T Q^{-1} \xi'(k)]$$

$$\gamma(k) = (c^T Q^{-1}) \xi'(k)$$

where

$$\phi' = Q\phi Q^{-1} = \begin{bmatrix} p_1 & 1 & 0 & \dots & 0 \\ p_2 & 0 & 1 & \dots & 0 \\ p_3 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ p_{2N} & 0 & 0 & \dots & 1 \\ p_{2N+1} & 0 & 0 & \dots & 0 \end{bmatrix}$$

$$c'^T = c^T Q^{-1} = [1 \ 0 \ 0 \ \dots \ 0]$$

$$g' = Qg = [g'_1 \ g'_2 \ \dots \ g'_{2N+1}]^T$$

The characteristic equation of ϕ' is easily shown to be

$$z^{2N+1} - p_1 z^{2N} - p_2 z^{2N-1} \dots - p_{2N} z - p_{2N+1} = 0$$

The characteristic equation of the transformed system is

$$z^{2N+1} - (p_1 - g'_1)z^{2N} - (p_2 - g'_2)z^{2N-1} - \dots - \dots - (p_{2N+1} - g'_{2N+1}) = 0,$$

each coefficient of which may be chosen at will by appropriate choice of the elements of g' . For a deadbeat error system,

$$g'_i = p_i, \quad i = 1, 2, \dots, 2N+1$$

Then

$$g = Q^{-1} g'.$$

APPENDIX - II

A second-order recursive lowpass digital filter was used in this study [11]. The algorithm can be described by

$$Y(k) = A \cdot Y(k-1) + B \cdot Y(k-2) + C \cdot X(k) \\ + D \cdot X(k-1) + E \cdot X(k-2)$$

In this equation $X(k)$ is the k th input (unfiltered) signal sample. $Y(k)$ is the k th output (filtered) sample, A , B , C , D , E are constants. These constants are determined from an equivalent 2nd order Butterworth low pass filter of cut-off frequency 120/100 Hz by the bilinear transformation method. The term recursive means that the output sample $Y(k)$ is a function of previous output samples $Y(k-1)$, $Y(k-2)$ as well as a function of several input samples, $X(k)$, $X(k-1)$, $X(k-2)$.

From a computational point of view, this algorithm requires less calculations than the non-recursive low pass filter.

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