

**FORWARD AND ITERATIVE INVERSE
KINEMATICS OF AN INDUSTRIAL ROBOT
USING LABVIEW**

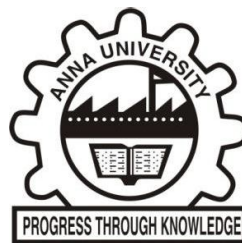
A THESIS

Submitted by

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